National Project 'Development of a Remote Controllable Decontamination Technique inside the Reactor Buildings'

Investigation into Contamination Status in the South on the First Floor of the Unit 1 Reactor Building

December 18, 2013 Tokyo Electric Power Company



1. Results of the previous investigations in the south on the first floor of the Unit 1 reactor building

- We conducted three investigations (June and October in 2011, and July 2012), obtained the data of radiation dose, and found the steam spouting from the torus room. (maximum 5,150mSv/h)
- In order to describe a more detailed plan for lowering dose, it is necessary to find the distribution of radiation dose and the dose data through the investigation with γ camera. Also, it is necessary to conduct a coring in order to determine if the penetration of contamination is present, for the steam blast was found in this area.





Penetration-part on the floor (where a steam blast from the torus was found at first by the accident)



Equipment funnel

*1: Above the floor *2: Approx. 60cm above the floor *3: Approx. 106cm above the floor *4 Above funnel *5 Above the penetration part on the floor

Figure 1. Results of investigation (July, 2012)

In the previous investigation, we measured the radiation dose at the height of 15 and 150 cm above the floor. We will measure at the height of 5 and 150 cm above the floor, and will take photos with γ camera.



2. Investigation area

- Dose rate will be measured at every 3-meter point at the height of 5 and 150 cm (represented as at Figure 2) in the south on the first floor. We will take photos with γ camera at the four points (represented as × at Figure 2)
- At each point. we will take photos from all directions with γ camera with various angles of elevation and rotation.



Figure 2. Investigation area (plan)



3. Structure of investigation apparatuses



4. Specifications of investigation apparatuses

Specifications

Measuring robot: Warrior (made by i-Robot) Weight: 222kg Length: 889 mm Width: 768 mm Height: 438 mm Operating time: 3 to 4 hours (with battery) Traveling velocity: Max. 12.9km/h

Relay robot: Packbot (made by i-Robot) Weight : Approx. 30kg Length: 700 mm Width: 530 mm Height: 190 mm Operating time: Approx. 8 hours (with battery) Travelling velocity: Maxim 9.36km/h







Figure 5. Packbot

5. Specifications of the γ camera

- A γ camera was developed by Hitachi Ltd. in the 'research and development project of unmanned system for disaster handling' of New Energy and Industrial Technology Development Organization (NEDO).
- Specification of the camera

Size: 340mm×430mm×467mm Weight: Approx. 80kg Measurable background dose rate (design point): 300mSv/h Detector: CdTe semiconductor detector (16 pixel×16 pixel) Distance correction function: Distance correction per pixel



Figure 6. γ camera



2013年01月17日 AUTO . 11時44分00秒 31.4 【待機中】 経過時間 00:00:10 测定開始 西面キャプチャ やり直し 測定終了判定 自動 王寿市 計測表示 mGv/h モノクロロカラ 測定時は異装モードに移行 全計数率 0.29kc 中心距離 129m 内部温度 12.3 ℃ 内部温度 7.3% HITACHI 終了

Figure 7. Operation screen of γ camera

Investigation area		Dec., 2013											Jan., 2014			Feb., 2014			Mar., 2014					
		18	19	20	21	22	23	24	25	26	27	28	29	30	31	Early	Mid.	End	E <u>ar</u> ly	Mid.	End	Early	Mid.	End
Investigation in the south (dose rate and γ camera)	In	ves		rep atic						ıp														
Coring samples in the south																								
Forming a plan for lowering dose (including data assessment)									/													/		
Work for lowering dose											Sta	art	inç	g ir	n the	e se	con	d ha	alf o	f FY	′201	4		

Table 1.Investigation schedule (plan)



[Reference] Needs for investigation in the south side on the first floor at Unit 1 reactor building

- In the south side on the first floor, investigations inside the primary containment vessel (PCV) (investigation inside the pedestal via the penetration X-6), investigation and repair work at PCV are planned in the second half in FY2015, requiring to form a decontamination plan.
- Specifying radiation dose via γ camera is necessary, in order to form a plan, in addition to measuring the dose rate.



[Reference] Coring method

The remote operated vehicle (ROV), 'MEISTeR' developed by Mitsubishi Heavy Industry has two arms: one arm equipped with core boring device and the other equipped with a chisel to cut core off All the equipments run by electricity, therefore there is no danger of oil leak



Figure 9. Traveling on stairs



Figure 10. Boring core

- Vehicle size: Length1250mm, Width700mm, Height1300mm
- Weight : Approx. 550kg (Vehicle:480kg, Core boring device: 70kg)
- Automatic following-tracking independent 4 crawlers (for travelling on ground) enable the vehicle to travel on stairs or rough/uneven ground with ease.

(However, the corridors inside the reactor building are too narrow for the vehicle to travel.)

 The vehicle automatically measures its center of gravity so that the upper equipments can be held at the right point. (Figure 9)

• The vehicle's two arms with seven axes enable the vehicle to do work such as core boring etc.

(Figure 10) 東京電力 National Project 'Development for a remote controllable decontamination technique inside the reactor buildings'

Plan of an investigation into contamination status in the south on the first floor at Units 1, 2, and 3 reactor buildings



1. Result of the site investigation in FY2012

- First floors at Units 1 to 3 reactor buildings (max. dose rate, up to 100Sv/h) were mainly investigated in a national project in FY2012. The result is as follows.
- Contribution rate for the dose rate at the height of 150cm from the floor ground from each contamination source (floor surface, wall, ceiling, hot spot, and others, mainly upper structure) was as follows:
 - 1. Contribution rate from the floor surface: 10 to 40%
 - 2. Contribution rate from the wall and ceiling: 5 to 15%
 - 3. Contribution rate from the hot spot: 10 to 40%
 - 4. Contribution rate from others mainly upper structure: 30 to 70%



Figure 1. Contribution rate to the height of 150cm from the floor surface (on the first floor at Unit 2 reactor building

- Contaminating nuclides are Cs134 and Cs137, and the existing ratio is 2 to 3 (after adjusting to the accident period, 1 to 1). Both are estimated originated in the accident. No α nuclide was found.
- Contamination remains at minute damages on the epoxy-painted surface. There was no penetrating contamination.



2. Objectives and areas of the investigation

Objectives

We aim to collect input data to accelerate the discussion on the dose reduction plan at the upper levels of the reactor buildings and the high dose area (the south side on the first floor of Unit 1 reactor building and the fifth floor of the Unit 2 reactor building) in cooperation with a national project 'forming a general plan for lowering dose.'

On-premise investigation area in FY2013

The second and third floor of Units 1 to 3 will be investigated. In addition, 1)the high dose areas on the first floor where the investigation was impossible in FY2012 and 2)the upper structures which are suspected to contribute to most of radiation dose (judging from the investigation results in FY2012) will be also investigated.



2. Objectives and areas of the investigation

		1 1		gation area an			
			Investigati				
Unit	Area and floor	Dose rate (Dosimeter)	Contamination distribution $(\gamma \text{ imager})$	Connative radiation source (Integral dosimeter)	Penetrating contamination (Core sampling)	Note	
	South side, 1 st floor	0	0	-	0	- Warrior (i-Robot*1) and ? camera (NEDO) for investigation - MESITeR. (Mitshubishi Heavy Industry*1) for coring	
- 1	Higher place, 1 st floor	0	0	—	_	- Lifting apparatus and γ camera (NEDO) for investigation	
384 CL• 1	Whole area, 2 nd floor	0	0	_	_	- Rosemary (CIT*1*2) and N-Visage (γ imager made in UK) for investigation	
	Whole area, 3 rd floor	0	0	_	_	- Rosemary (CIT ^{*1*2}) and N-Visage (γ imager made in UK) for investigation	
	Higher place, 1 st floor	0	0	0	_	 Lifting apparatus and γ camera (NEDO) for investigation Workers will attach the integral dosimeter (Quixel Badge) for connative radiation source investigation 	
7	Whole area, 2 nd floor	0	0	—	_	- Rosemary (CIT ^{*1*2}) and N-Visage (γ imager made in UK) for investigation	
2 till	Whole area, 3rd floor	0	0	—	_	- Rosemary (CIT ^{*1*2}) and N-Visage (γ imager made in UK) for investigation	
	Whole area, 5th floor (operation floor)	0	0	—	0	- N-Visage (γ imager made in UK) for investigation - MESITeR (Mitshubishi Heavy Industry*1) for coring	
33 機	Higher place, 1 st floor	0	0	_	_	- Lifting apparatus and γ camera (NEDO) for investigation	
	Whole area, 2 nd floor	0	0	_	_	- Rosemary (CIT ^{*1*2}) and N-Visage (γ imager made in UK) for investigation	

Figure 1. Investigation area and item



Investigation area	Dec., 2013			Jan., 2014			Feb., 2014			Mar., 2014			Apr., 2014			How to make use of the results of dose lowering based on the investigation results	
	Early	Mid.	End	Early	Mid.	End	Early	Mid.	End	Early	Mid.	End	Early	Mid.	End	lowening based on the investigation results	
South side on the first floor at Unit 1 Dose m	easurinç	g and pl	noto she	ooting w	/ith γ (camera	(Hitach	i)	Sampli	ng core	s (Mitsı	ubishi)				Contributing to forming a decontamination plan starting in the second half of FY2014	
Higher places on the first floor at Units 1, 2, and 3		Ins	talling a	in integi structure	ral dosir es (Tosł	neter a tiba)	t upper		. [Dose me sho	easurin oting wi	g at hig th γ c	her plac amera (e and p Hitachi	:	Contributing to 1)the decontamination work on the first floor at Unit 1 (from the second half of FY2014) and 2) forming a decontamination plan on the first floor at Unit 3	
Second and third floors at the reactor build. at Unit 1						Do	se mea	suring a	and pho	to shoo	ting wit	hγca	mera (⊦	litachi)		Contributing to forming a decontamination plan at higher floors	
Second and third floors at the reactor build. at Unit 2							Dose r	neasurii	ng and	photo s	hooting	with γ	camer	a (Hitad	chi)	Contributing to forming a decontamination plan at higher floors	
Second floor at the reactor build. at Unit 3							Do	se mea	suring a	and pho	to shoo	ting wit	hγca	mera (F	litachi)	Contributing to forming a decontamination plan at higher floors	
Fifth floor (operation floor) at the reactor build. at Unit 2					Videot shoo	aping a ting wit	nd dose h γ ca	e distribi mera (H	ution m litachi),	easuren core sa	nent (To ampling	oshiba) (Mitsul	, photo pishi)			Contributing to discussion and judgment on how to remove the fuel from Unit 2 planned in the first half of FY2014	

Table 2. Investigation schedule (plan)

* The work schedule is subject to change due to the adjustment for the areas at the site.

Details of the structure of investigation apparatuses and investigation points will be reported separately before each work starts.



<Reference> Investigation area on the first and second floors at Unit 1



- Investigation area in FY 2012 (already completed)
- Investigation area in FY2013 (excluding the investigation area for the higher place^{*1})
 - *1: Investigation area for the higher places on the first floor at Unit 1 will be confirmed based on the measurement data by 3D laser obtained after December, 2013.

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<Reference> Investigation area on the third floor at Unit 1



Third floor at Unit 1

- Investigation area in FY 2012 (already completed)
- 「「「「」: Investigation area in FY2013

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<Reference> Investigation area on the first and second floors at Unit 2



- "///////. "////////
- Investigation area in FY 2012 (already completed)
 - /////// : Investigation area in FY2013 (excluding the investigation area for the higher place^{*1})
 - *1: Investigation area for the higher places on the first floor at Unit 2 will be confirmed based on the measurement data by 3D laser obtained after December, 2013.



<Reference> Investigation area on the third and fifth floors at Unit 2



<Reference> Investigation area on the second and third floors at Unit 3



- //////: Investigation area in FY2012 (already completed)
- Investigation area in FY2013 (excluding the investigation area for the higher place^{*1})
 - *1: Investigation area for the higher places at Unit 3 will be confirmed based on the

